





Multithreading - 1

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Outline

- Introduction
- What is a thread
- Why multithreading
- Multithreading in Geant4
- Multithreading Geant4 application

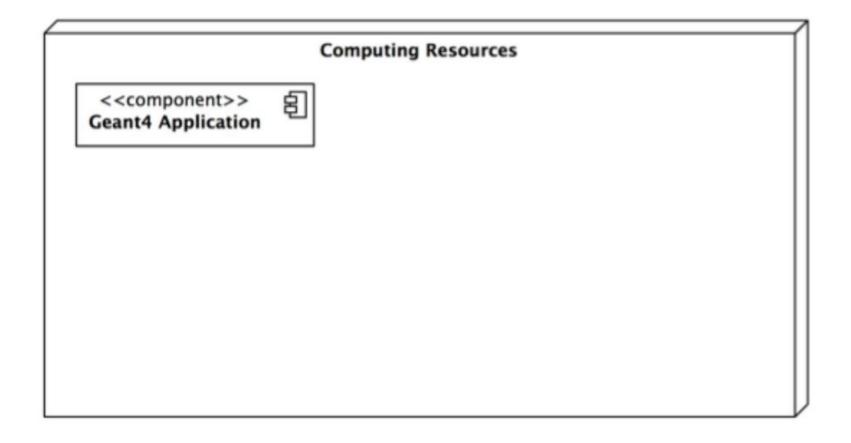
Introduction

- Modern CPU architectures:
 - Increasing number of processors & memory, but memory cost scales slower => Less memory/core
- Memory and its access will limit number of concurrent processes running on single chip
- Solution: add parallelism in the application code
- Geant4 needs back-compatibility with user code and simple approach (physicists != computer scientists)

What Is a Thread

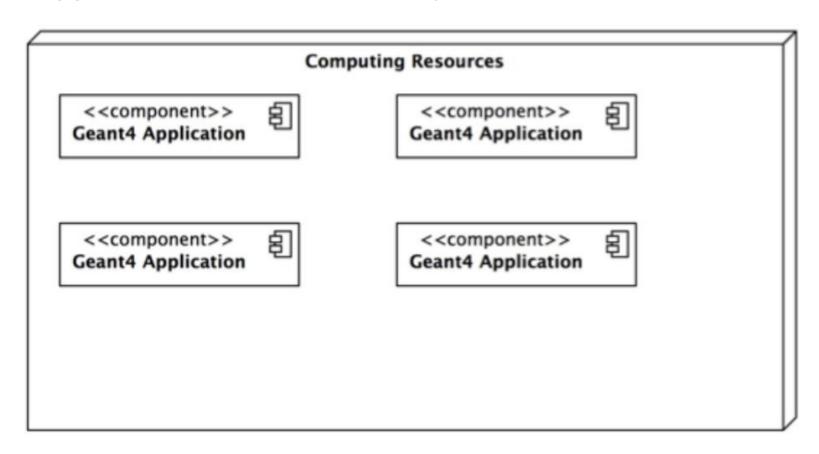
What Is a Thread?

Sequential application - one core



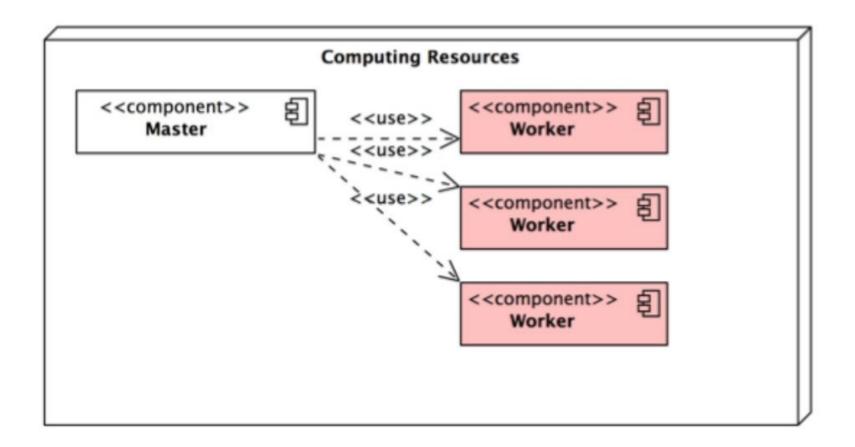
What Is a Thread? (2)

Sequential application – start N (cores/CPUs) copies of an application if it fits in memory



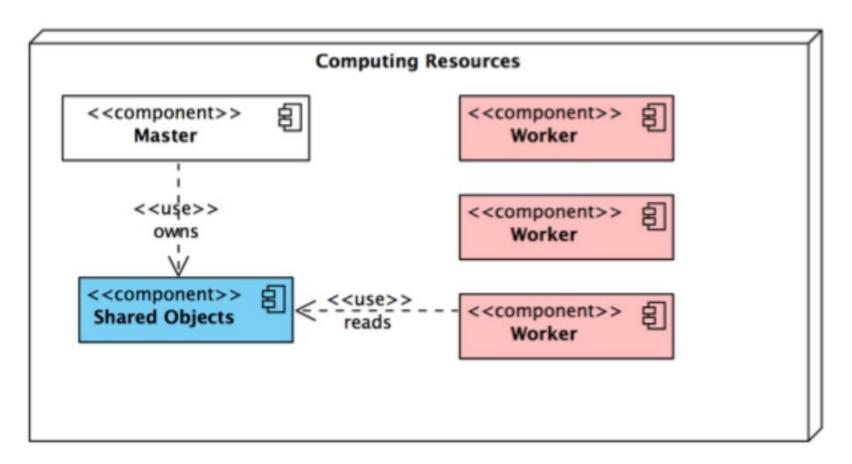
What Is a Thread? (3)

MT application – a single application starts threads.

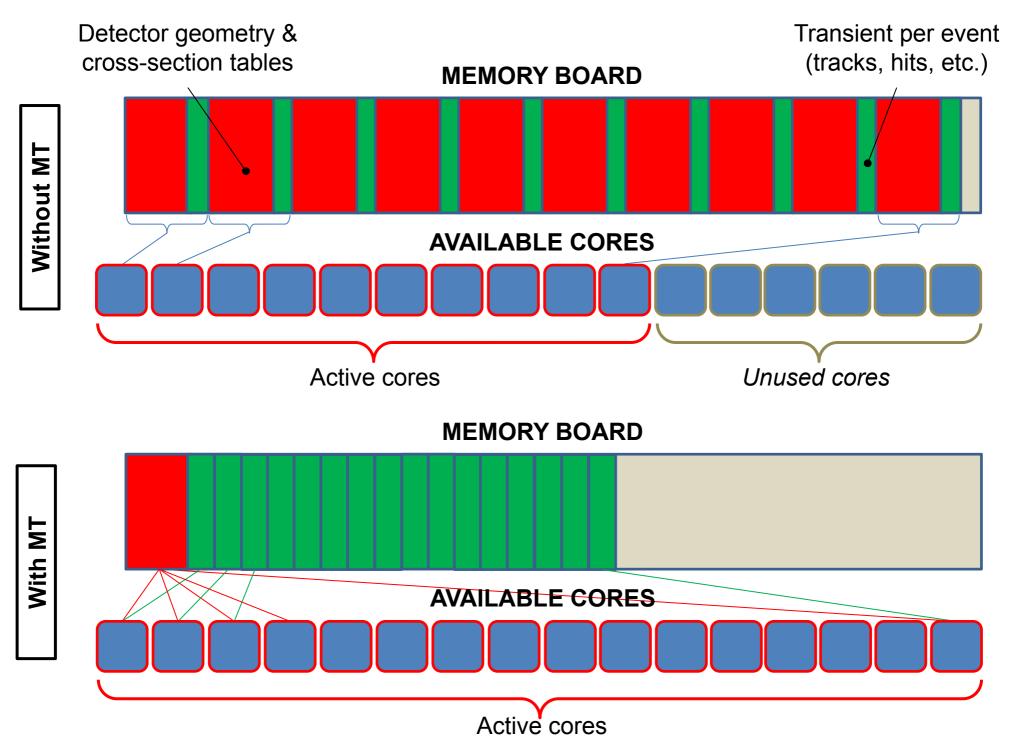


What Is a Thread? (4)

 Memory reduction: when shared objects are introduced, memory of N threads is less than memory used by N copies of the application



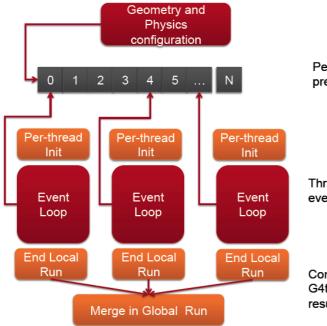
Why Multithreading



Multithreading in Geant4

Multi-threading in Geant4

 General design choice: event level parallelism via multi-threading (POSIX based, in 10.5 migration from POSIX threading to C++11 threading)



Per-event seeds preprepared in a "queue"

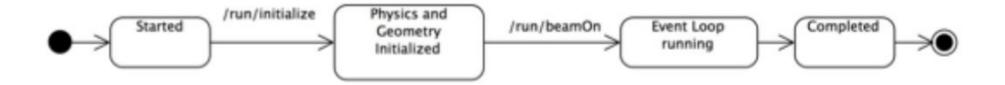
Threads compete for next event to be processed

Command line scoring and G4tools automatically merge results from threads

- Each worker thread proceeds independently
 - Initializes its state from a master thread
 - Identifies its part of the work (events)
 - Generates hits in its own hitscollection
- Geant4 automatically performs reductions (accumulation) when using scorers, G4Run derived classes or g4tools

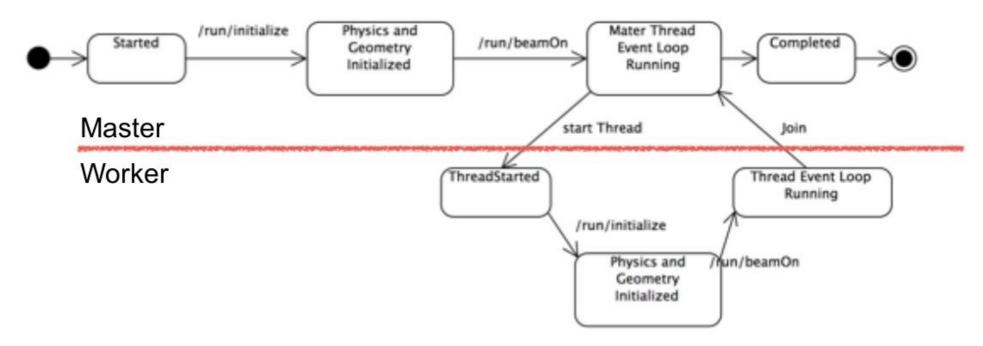
Simplified Master / Worker Model

 A Geant4 application (in MT mode) can be seen as simple finite state machine



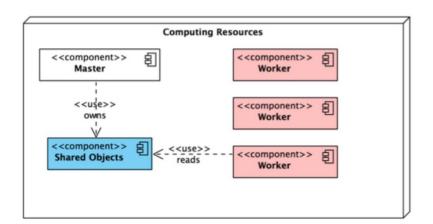
Simplified Master / Worker Model (2)

- A Geant4 application (in MT mode) can be seen as simple finite state machine
- Threads do not exists before first /run/beamOn
- When master starts the first run spawns threads and distribute work!



Shared Memory

- To reduce memory footprint threads must share at least part of the objects
- General rule in Geant4: threads can share whatever is invariant during the event loop (e.g. threads do not change these objects while processing events, these are used "read-only")
 - Geometry definition
 - Electromagnetic physics tables



Shared? Private?

- In the multi-threaded mode
 - data that is stable during the event loop is shared among threads, while
 - data that is transient during the event loop is thread-local.
- Shared by all threads: stable during the event loop
 - Geometry
 - Particle definition
 - Cross-section tables
 - User-initialization classes

- Thread-local: dynamically changing for every event/track/step
 - All transient objects such as run, event, track, step, trajectory, hit, etc.
 - Physics processes
 - Sensitive detectors
 - User-action classes

Geant4 MT

- Event level parallelism via multithreading (POSIX based)
- Built on top of experience of G4MT prototypes
 - Capitalizing the work started back in 2009 by X.Dong and G.Cooperman,
 Northeastern University
- Main design driving goal: minimize user-code changes
- Integrated into Version 10.0 codebase
 - MT code integrated into G4

- Public release
- All functionalities ported to MT



- Proof of principle
- Identify objects to be shared
- First testing

- API re-design
- Example migration
- Further testing
- First optimizations

- Further Refinements
- Focus on further performance improvements

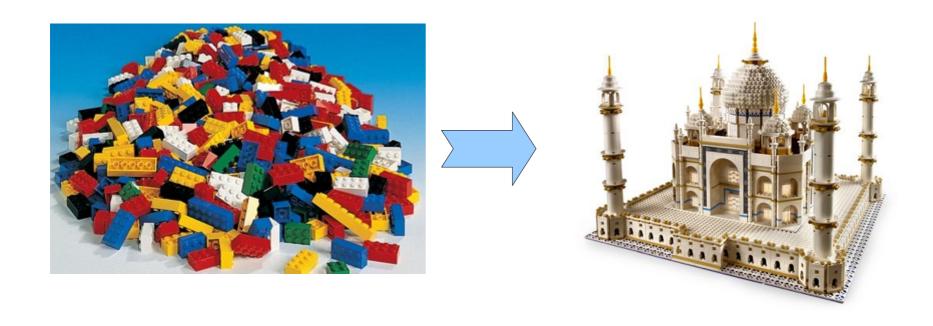
Geant4 10.00

- This is the first release (December 2013) with multithreading capability with event parallelism
 - Two build options: Multithreaded and Sequential mode, selection via a cmake configuration option -DGEANT4_BUILD_MULTITHREADED=ON
- Maximum back-compatibility with user code however some API had to changed to enable MT (this is why this is a major release)
 - An application developed for Geant4 version 9.6 can be used without changing the code in sequential mode (except for other mandatory modifications not MT-related)
 - An MT-ready application, can also run in sequential mode without changing the code (but not vice-versa)

Multithreading Geant4 Application

Geant4 MT and User Application

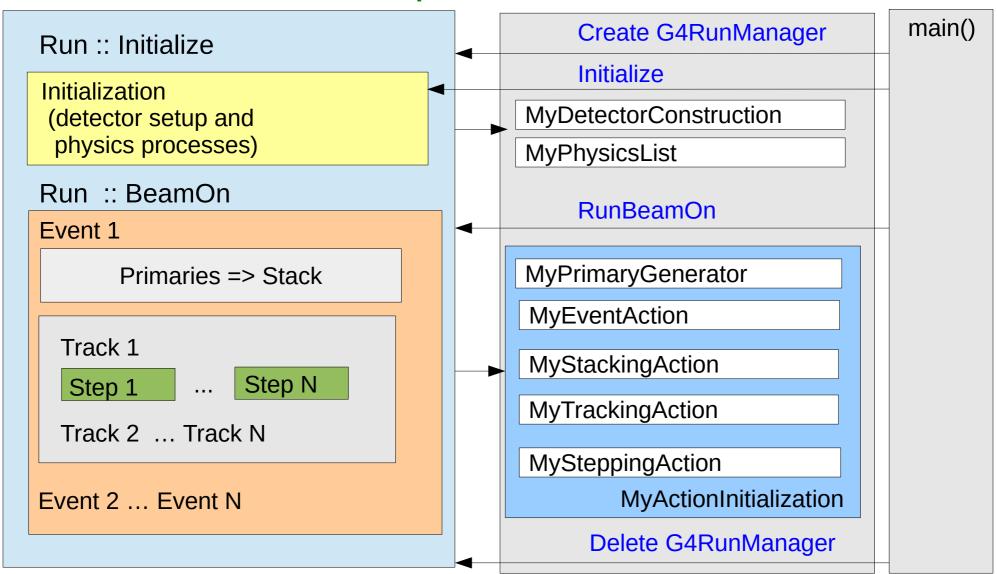
 Geant4 provides building blocks (bricks) Users have to assemble them to describe their scenario in their application program



Towards MT Application

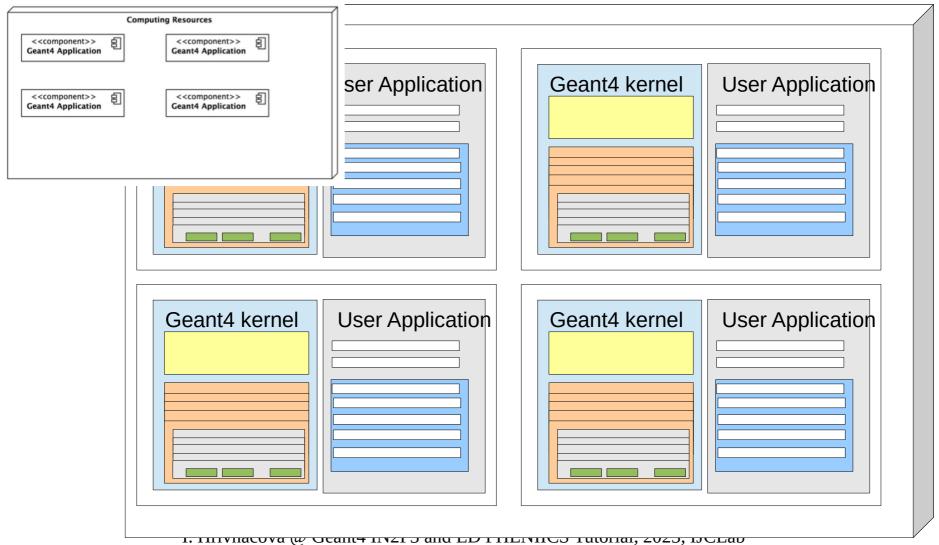
- Geant4 kernel takes care of steering event processing on workers
 - Use new G4RunManagerFactory class to create a G4RunManager derived class for steering MT run
- New Geant4 virtual methods/classes to be implemented in a user code
 - G4VUserActionInitialization mandatory
 - G4VUserDetectorConstruction::ConstructSDandField() for applications with field and/or sensitive detectors
 - G4UserWorkerThreadInitialization optional, for applications which want/need to customize some aspects of thread behavior
- Make your application thread-safe

Geant4 Kernel & User Application In Sequential Mode

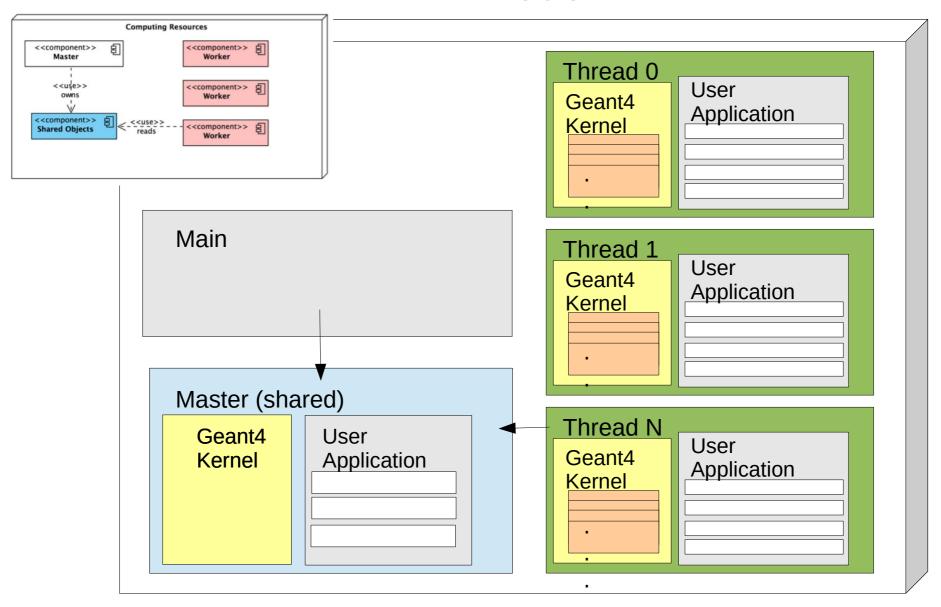


User Application and Geant4 Kernel In Sequential Mode

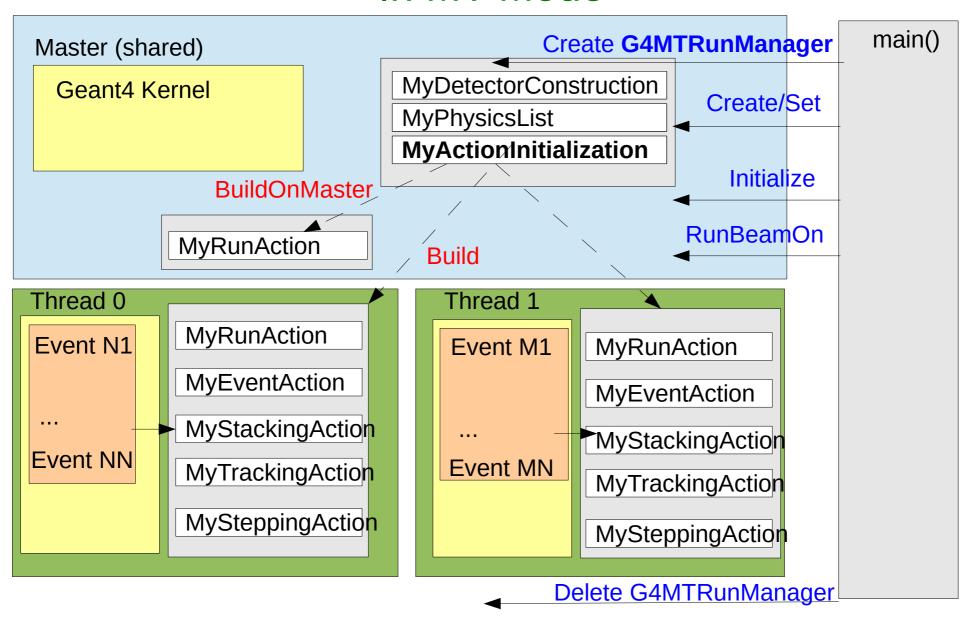
 Sequential application – start N (cores/CPUs) copies of an application if it fits in memory



User Application and Geant4 Kernel In MT Mode



User Application and Geant4 Kernel In MT Mode



main()

- Geant4 does not provide the main().
- In your main(), you have to
 - Construct G4RunManager derived class using G4RunManagerFactory
 - Define your initialization classes: MyDetectorConstruction and MyPhysicsList and set them to G4RunManager
 - Define your primary generator class (MyPrimaryGenerator) using your MyActionInitialization class and set it to G4RunManager
- You can also
 - Define optional user action classes and set them to G4RunManager using your ActionInitialization class
 - Define Geant4 visualization and (G)UI session via G4VisExecutive and G4UIExecutive and/or your persistency manager

main() - sequential

```
#include "DetectorConstruction.hh"
                                                          exampleED.cc
#include "ActionInitialization.hh"
#include "G4RunManager.hh"
#include "FTFP BERT.hh"
int main(int argc,char** argv)
  // Create User Interface and enter in interactive session (1)
  // Construct the default run manager
  G4RunManager* runManager = new G4RunManager;
  // Detector construction
  runManager->SetUserInitialization(new ED::DetectorConstruction());
  // Physics list
  G4VModularPhysicsList* physicsList = new FTFP_BERT; runManager->SetUserInitialization(physicsList);
  // User action initialization
  runManager->SetUserInitialization(new ED::ActionInitialization());
  // Create User Interface and enter in interactive session
```

main() - MT

```
#include "DetectorConstruction.hh"
                                                       exampleED.cc
#include "ActionInitialization.hh"
#include "G4RunManagerFactory.hh"
                                                           The default run
#include "FTFP BERT.hh"
                                                           manager type
int main(int argc, char** argv)
                                                           supports MT
{
  // Create User Interface and enter in interactive session (1)
  // Construct the default run manager
  auto* runManager =
    G4RunManagerFactory::CreateRunManager(G4RunManagerType::Default);
  // Detector construction
  runManager->SetUserInitialization(new ED::DetectorConstruction());
  // Physics list
  G4VModularPhysicsList* physicsList = new FTFP_BERT;
  runManager->SetUserInitialization(physicsList);
  // User action initialization
  runManager->SetUserInitialization(new ED::ActionInitialization());
  // Create User Interface and enter in interactive session
```

User Action Initialization

- The initialization and action classes which are called during event processing MUST be defined all together in the user action initialization class derived from G4VUserActionInitialization abstract base class.
 - Note that use of this class is mandatory for multithreading processing
- Implement the virtual method Build(), where you
 - Instantiate all initialization and action classes called during event processing
 - This method is called in MT mode on the workers
- Optionally, implement the virtual method BuildForMaster(), where you
 - Instantiate all initialization and action classes called during event processing which should be build on master
 - Typically, RunAction is created both on master and workers

```
#include "G4VUserActionInitialization.hh"

namespace ED
{
class ActionInitialization : public G4VUserActionInitialization
{
  public:
    ActionInitialization();
    virtual ~ActionInitialization();
    virtual void Build() const;
};

Sequential
```

```
#include "ActionInitialization.hh"
#include "PrimaryGeneratorAction.hh"
#include "EventAction.hh"

namespace ED
{
ActionInitialization::ActionInitialization()
{}

void ActionInitialization::Build() const
{
SetUserAction(new PrimaryGeneratorAction);
SetUserAction(new EventAction);
}
}
```

Action Initialization - .hh - MT-ready

ActionInitialization.hh

```
#include "G4VUserActionInitialization.hh"
namespace ED
class ActionInitialization : public G4VUserActionInitialization
  public:
    ActionInitialization();
                                                    Function called
    virtual ~ActionInitialization();
                                                    only in MT mode
    virtual void Build() const;
    virtual void BuildForMaster() const;
};
```

Action Initialization - .cc - MT-ready

ActionInitialization.cc

```
#include "ActionInitialization.hh"
#include "PrimaryGeneratorAction.hh"
#include "EventAction.hh"
namespace ED
// ...
void ActionInitialization::Build() const
  SetUserAction(new PrimaryGeneratorAction);
  SetUserAction(new EventAction);
                                                   Function called
                                                   only in MT mode
  SetUserAction(new RunAction);
}
void ActionInitialization::BuildForMaster() const
  SetUserAction(new RunAction);
}
```

Geometry

- To describe your detector you have to derive your own concrete class from G4VUserDetectorConstruction abstract base class.
- Implement the virtual method Construct(), where you
 - Instantiate all necessary materials
 - Instantiate volumes of your detector geometry
 - Optionally, create regions, visualization attributes
 - All these geometry objects (materials, volumes, ...) are created in shared memory (on master)
- Optionally, implement the virtual method ConstructSDandField(), where you
 - Instantiate your sensitive detector classes and set them to the corresponding logical volumes
 - Instantiate magnetic (or other) field
 - Using ConstructSDanField() is mandatory with multi-threading
 - Sensitive detectors and field are created on workers

Physics

- Physics list is instantiated in main()
 - Its is created in shared memory (on master)
- Physics lists provided in Geant4 are MT-ready
 - Nothing to be done on the user side in this case
 - Particles are constructed via call to ConstructParticle() in shared memory (on master)
 - Physics processes are constructed via call to ConstructProcess() on workers
- If you define your own physics list
 - Make sure that all process objects are instantiated in the ConstructProcess() method and NOT in the physics list constructor
 - If it includes ions, add G4GenericIon::GenericIonDefinition() into ConstructParticle() method. This ensures that all ions (including light ions such as deuteron, alpha) work properly.

Scoring

- Geant4 sensitive, hits collections are MT ready
 - Hits objects, as well as sensitive detectors, are instantiated on workers, that's why the G4Allocator declared with hit class need to be defined thread-local - add G4ThreadLocal keyword

```
MyHit.hh sequential
```

```
extern G4Allocator<MyHit>* MyHitAllocator;

MyHit.cc sequential
```

G4Allocator<MyHit>* MyHitAllocator = 0;

MyHit.hh MT-ready

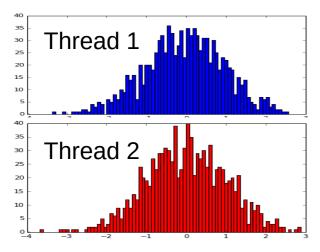
```
extern G4ThreadLocal G4Allocator<MyHit>* MyHitAllocator;
```

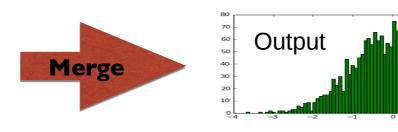
MyHit.cc MT-ready

G4ThreadLocal G4Allocator<MyHit>* MyHitAllocator = 0;

Analysis

- Geant4 analysis tools are MT-ready
- Histograms & profiles:
 - Each thread owns its own copy of given histograms & profiles
 - At the end of the run workers objects are "merged" into a single one on master
 - A single file with merged histograms and profiles will be produced
- When using G4AnalysisManager with histograms, the UserRunAction class must be instantiated both on master and workers





Analysis (2)

- Ntuples
 - Each thread owns a copy of ntuple
 - Not merged by default
- Output files
 - Each thread will write out a separate file, file names are generated automatically:
 - fileName[_ntupleName]_tid.ext
 - where tid = thread Identifier (0,1,2, ...), ext = root, xml, csv, hbook
- When using Root output merging can be activated using
 - analysisManager->SetNtupleMerging(true);

Visualization

- Geant4 visualization is MT-ready
- Visualization is done by master thread based on event keeping
- Events are drawn directly from worker threads as soon as any are ready

User Interface

- User interacts with application typing UI commands
 - Master thread "accumulates" the commands and passes the commands stack to all the threads at the beginning of a run
 - Threads execute the same commands sequence as master thread
- However some commands make sense only in master thread (e.g. the one modifying the geometry)
 - UI commands can be marked as "not to be broadcasted" via G4UIcommand::SetToBeBroadcasted(false);
- Do not forget this step if you implement user-defined UI commands

Conclusions

- Geant4 collaboration made a big effort to make writing Geant4 multi-threading application easy
 - We believe that just following the instructions is enough for simple applications
- Parallelism is however a tricky business:
 - We will speak about race conditions in the second part of this presentation